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1YGB - N456 PAPER C - QUESTION 1

START BY FINDING $\vec{AB}$

$$\vec{AB} = \underline{b} - \underline{a} = (17\underline{i} - 5\underline{j}) - (2\underline{i} + 5\underline{j}) = 15\underline{i} - 10\underline{j}$$

FIND THE WORK DONE (IN OR OUT) BY THE FORCE

$$\begin{aligned} W &= \underline{F} \cdot \underline{r} = (2.6\underline{i} - 0.1\underline{j}) \cdot (15\underline{i} - 10\underline{j}) \\ &= 39 + 1 = 40 \text{ J} \end{aligned}$$

BY ENERGIES

WORK IN = GAIN IN KINETIC ENERGY

$$40 = \frac{1}{2} m v^2$$

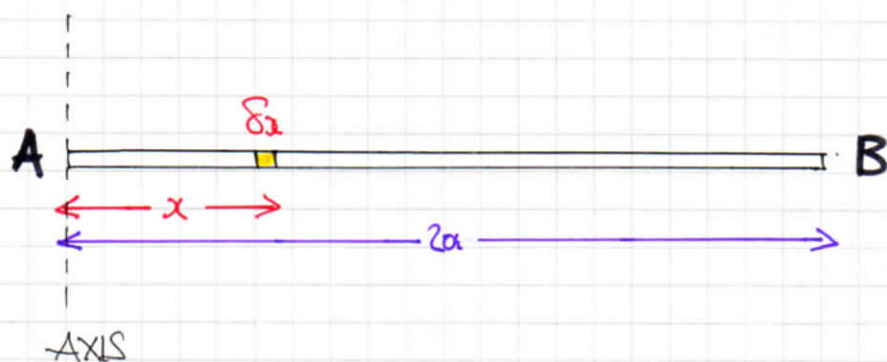
$$40 = \frac{1}{2} \times 0.2 \times v^2$$

$$v^2 = 400$$

$$v = \underline{20 \text{ ms}^{-1}}$$

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LOOKING AT THE DIAGRAM BELOW



IF THE MASS OF THE ROD IS M , THEN $\rho = \frac{M}{2a}$
(MASS PER UNIT LENGTH)

- THE MASS OF INFINITESIMAL LENGTH δx IS $\rho \delta x$
- THE MOMENT OF INERTIA OF THE "INFINITESIMAL" ABOUT THE AXIS THROUGH A IS

$$(\rho \delta x) x^2$$

- SUMMING UP ALL THESE MOMENTS OF INERTIA FROM A TO B AND TAKING LIMITS

$$I = \int_{x=0}^{x=2a} \rho x^2 dx = \left[\frac{1}{3} \rho x^3 \right]_{x=0}^{x=2a} = \frac{1}{3} \rho (8a^3) - 0$$

$$= \frac{1}{3} \left(\frac{M}{2a} \right) (8a^3) = \frac{4}{3} Ma^2$$

~~As required~~

1XGB - M456 PART C - QUESTION 3TOTAL POTENTIAL ENERGY, AS A FUNCTION OF θ , IS GIVEN BY

$$V(\theta) = \frac{1}{2}mga(4\sin\theta - 1)^2 - 4mga\sin 2\theta + \text{CONSTANT}$$

LOOKING FOR EQUILIBRIUM POSITIONS

$$V'(\theta) = 4mga(4\sin\theta - 1)\cos\theta - 8mga\cos 2\theta$$

$$V'(\theta) = 4mga[(4\sin\theta - 1)\cos\theta - 2\cos 2\theta]$$

$$V'(\theta) = 4mga[4\sin\theta\cos\theta - \cos\theta - 2\cos 2\theta]$$

$$V'(\theta) = 4mga[2\sin 2\theta - \cos\theta - 2\cos 2\theta]$$

SETTING FOR ZERO

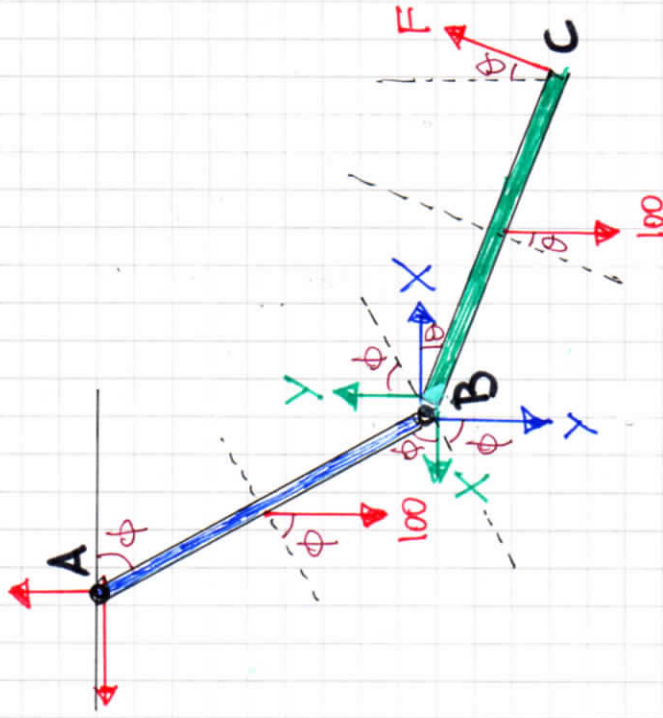
$$0 = 4mga[2\sin 2\theta - \cos\theta - 2\cos 2\theta]$$

$$2\sin 2\theta - \cos\theta - 2\cos 2\theta = 0$$

AS REQUIRED

LYGB - N456 PAGE C - QUESTION 4

STARTING WITH A DETAILED DIAGRAM



$$\tan \theta = \frac{3}{4}, \quad \sin \theta = \frac{3}{5}, \quad \cos \theta = \frac{4}{5}$$

LET WRITED LOSS OF GENERALITY $|AB| = |BC| = 2$

a) TAKING MOMENTS OF BC, ABOUT B

$$\Rightarrow F \times 2 = 100 \cos \theta \times 1$$

$$\Rightarrow 2F = 100 \times \frac{4}{5}$$

$$\Rightarrow F = 40 \text{ N}$$

b) SHOWING FORCES ON THE ROD BC (GREEN FORCES)

$$(1): Y + F \cos \theta = 100 \quad (\rightarrow): F \sin \theta = X$$

$$Y + 40 \times \frac{4}{5} = 100 \quad X = 40 \times \frac{3}{5}$$

$$Y = 68 \text{ N} \quad X = 24 \text{ N}$$

c) TAKING MOMENTS OF AB ABOUT A (BLUE FORCES)

$$\Rightarrow 100 \cos \phi \times 1 + Y \cos \phi \times 2 = X \sin \phi \times 2$$

$$\Rightarrow 100 \cos \phi + 136 \cos \phi = 48 \sin \phi$$

$$\Rightarrow 236 \cos \phi = 48 \sin \phi$$

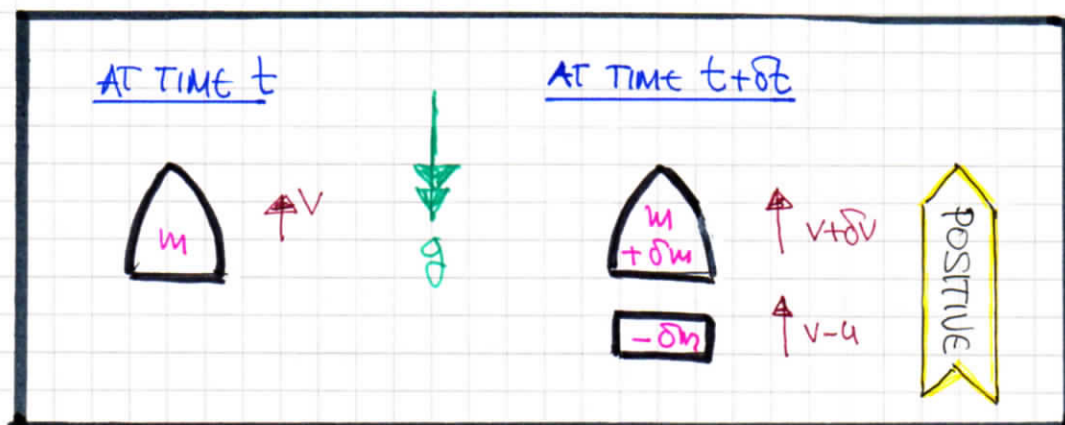
$$\Rightarrow \frac{\sin \phi}{\cos \phi} = \frac{236}{48}$$

$$\Rightarrow \tan \phi = \frac{59}{12}$$

$$\Rightarrow \phi \approx 78.5^\circ$$

YGB - MISS PAGE C - QUESTION 5

a) STARTING WITH THE USUAL MOMENTUM / IMPULSE DIAGRAM



BY THE IMPULSE-MOMENTUM PRINCIPLE

$$\Rightarrow -mg \delta t = [(m + \delta m)(v + \delta v) + (-\delta m)(v - u)] - [mv]$$

$$\Rightarrow -mg \delta t = \cancel{mv} + m\delta v + v\delta m + \delta m\delta v - \cancel{v\delta m} + u\delta m - \cancel{mv}$$

$$\Rightarrow -mg \delta t = m\delta v + u\delta m + \delta m\delta v$$

$$\Rightarrow -mg = m \frac{\delta v}{\delta t} + u \frac{\delta m}{\delta t} + \frac{\delta m \delta v}{\delta t}$$

TAKING LIMITS AND REARRANGE FOR THE ACCELERATION

$$\Rightarrow -mg = m \frac{dv}{dt} + u \frac{dm}{dt}$$

$$\Rightarrow \frac{dv}{dt} = -g - \frac{u}{m} \frac{dm}{dt}$$

NEXT, AS THE EJECTION RATE OF THE FUEL IS CONSTANT

$$\Rightarrow \frac{dm}{dt} = -\lambda, \text{ SUBJECT TO } t=0, m=M$$

$$\Rightarrow m = M - \lambda t$$

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COMBINING THE LAST TWO EXPRESSIONS

$$\Rightarrow \frac{dv}{dt} = -g - \frac{u}{M-\lambda t} (-\lambda)$$

$$\Rightarrow \frac{dv}{dt} = \frac{u\lambda}{M-\lambda t} - g$$

FINALLY FOR IMMEDIATE LIFT OFF $\frac{dv}{dt} > 0$, AT $t=0$

$$\Rightarrow \frac{u\lambda}{M} - g > 0$$

$$\Rightarrow u\lambda - gM > 0$$

$$\Rightarrow u\lambda > Mg$$

$$\Rightarrow \lambda > \frac{Mg}{u} \quad \text{AS REQUIRED}$$

b)

SOLVING THE O.D.E BY DIRECT INTEGRATION - FIRST

WE REQUIRE TO FIND THE TIME WHEN $m = \frac{3}{4}M$

$$\Rightarrow m = M - \lambda t$$

$$\Rightarrow \frac{3}{4}M = M - \left(\frac{3Mg}{u}\right)t$$

$$\Rightarrow \frac{3Mg}{u}t = \frac{1}{4}M$$

$$\Rightarrow t = \frac{u}{12g}$$

SOLVING THE O.D.E, SUBJECT TO $t=0, v=0$,

$$\Rightarrow \int dv = \left(\frac{u\lambda}{M-\lambda t} - g \right) dt$$

$$\Rightarrow \int dv = \left(\frac{u \frac{3Mg}{u}}{M - \frac{3Mg}{u}t} - g \right) dt$$

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$$\Rightarrow l \, dv = \left(\frac{3Mg}{m - \frac{3Mgt}{u}} - g \right) dt$$

$$\Rightarrow l \, dv = \left(\frac{3g}{1 - \frac{3gt}{u}} - g \right) dt$$

$$\Rightarrow l \, dv = \left(\frac{3ug}{u - 3gt} - g \right) dt$$

$$\Rightarrow \int_{v=0}^v l \, dv = \int_{t=0}^{t=\frac{u}{12g}} \frac{3ug}{u - 3gt} - g \, dt$$

$$\Rightarrow [v]_0^v = \left[\frac{3ug}{-3g} \ln|u - 3gt| - gt \right]_{t=0}^{t=\frac{u}{12g}}$$

$$\Rightarrow v = \left[-u \ln|u - 3gt| - gt \right]_{t=0}^{t=\frac{u}{12g}}$$

$$\Rightarrow v = \left[u \ln|u - 3gt| + gt \right]_{t=\frac{u}{12g}}^{t=0}$$

$$\Rightarrow v = [u \ln u] - \left[u \ln \left| u - 3g \left(\frac{u}{12g} \right) \right| + g \left(\frac{u}{12g} \right) \right]$$

$$\Rightarrow v = u \ln u - u \ln \left(\frac{3}{4}u \right) - \frac{1}{12}u$$

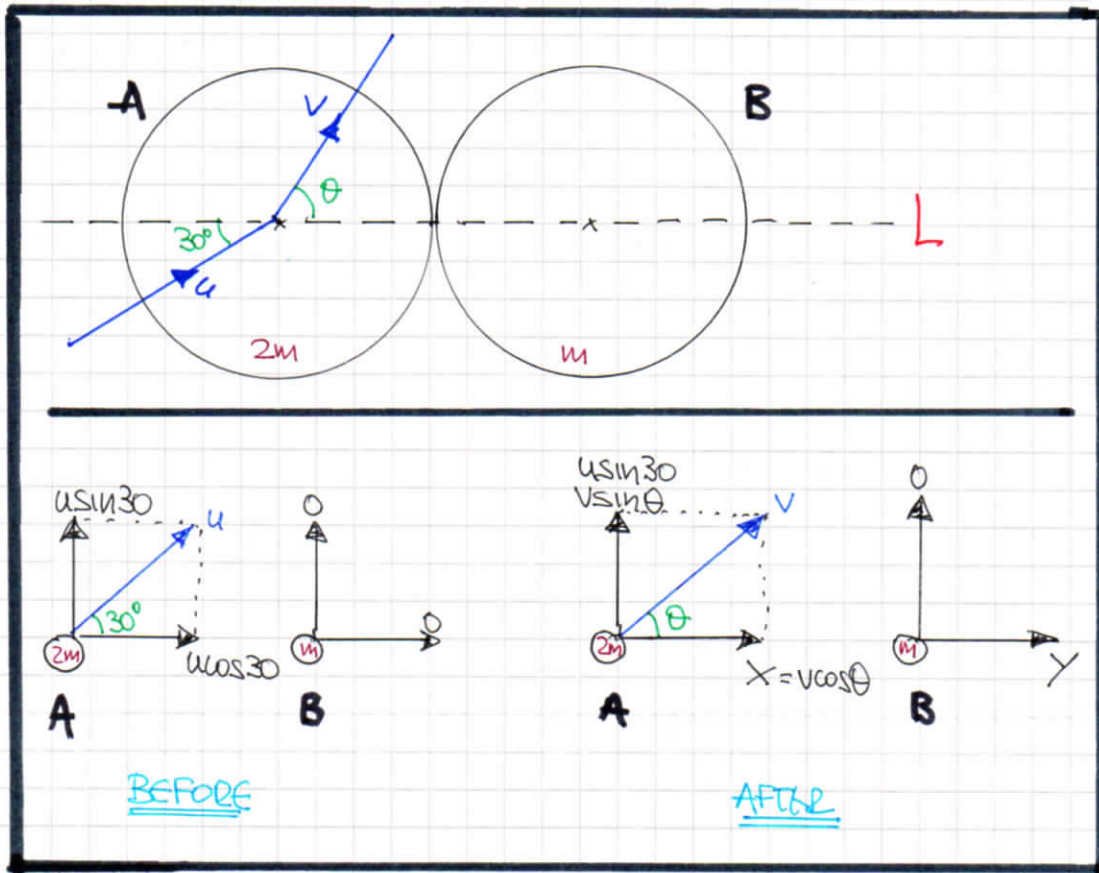
$$\Rightarrow v = u \ln \left(\frac{u}{\frac{3}{4}u} \right) - \frac{1}{12}u$$

$$\Rightarrow v = u \ln \frac{4}{3} - \frac{1}{12}u$$

$$\Rightarrow \underline{v = \left(\ln \frac{4}{3} - \frac{1}{12} \right) u}$$

1YGB - M456 PAGE C - QUESTION 6

a) STARTING WITH A USUAL DIAGRAM FOR THE COLLISION



BY CONSERVATION OF MOMENTUM ALONG L

$$\Rightarrow 2mu \cos 30^\circ + 0 = 2mX + mY$$

$$\Rightarrow 2X + Y = 2u \cos 30^\circ$$

$$\Rightarrow \boxed{2X + Y = \sqrt{3}u}$$

BY RESTITUTION ALONG

$$\Rightarrow \frac{Y - X}{u \cos 30^\circ} = e$$

$$\Rightarrow -X + Y = eu \cos 30^\circ$$

$$\Rightarrow -X + Y = \frac{\sqrt{3}}{2}eu$$

$$\Rightarrow \boxed{-2X + 2Y = \sqrt{3}eu}$$

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SOLVING THE EQUATIONS VIEWS BY ADDITION

$$\Rightarrow 3Y = \sqrt{3}u + \sqrt{3}eu$$

$$\Rightarrow 3Y = \sqrt{3}u(1+e)$$

$$\Rightarrow \underline{Y = \frac{\sqrt{3}}{3}u(1+e)}$$

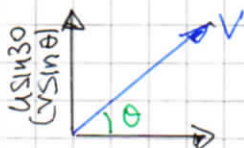
AND $X = Y - \frac{\sqrt{3}}{2}eu$

$$\Rightarrow X = \frac{\sqrt{3}}{3}u(1+e) - \frac{\sqrt{3}}{2}eu = \frac{\sqrt{3}}{3}u + \frac{\sqrt{3}}{3}eu - \frac{\sqrt{3}}{2}eu$$

$$\Rightarrow X = \frac{\sqrt{3}}{3}u - \frac{\sqrt{3}}{6}eu$$

$$\Rightarrow \underline{X = \frac{\sqrt{3}}{6}u(2-e)}$$

SPEED OF A - NO MOMENTUM EXCHANGE $\perp$ TO L



$$X = \frac{1}{6}\sqrt{3}u(2-e)$$

$$|V|^2 = (u \sin 30)^2 + X^2$$

$$|V|^2 = \frac{1}{4}u^2 + \frac{1}{12}u^2(2-e)^2$$

$$|V|^2 = \frac{1}{12}u^2 [3 + (2-e)^2]$$

$$|V|^2 = \frac{1}{12}u^2 [e^2 - 4e + 7]$$

$$\underline{|V|_A = u \sqrt{\frac{e^2 - 4e + 7}{12}}}$$

SPEED OF B

SIMPLY FOUND ABOUT THE "PERPENDICULAR TO L " COMPONENT IS ZERO

$$\underline{|V_B| = \frac{1}{3}\sqrt{3}u(1+e)}$$

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b) KE BEFORE THE COLLISION

$$\frac{1}{2}(2m)u^2 = mu^2$$

KE AFTER THE COLLISION

$$\begin{aligned} & \frac{1}{2}(2m)v_A^2 + \frac{1}{2}m v^2 \\ &= m \left(\frac{u^2(e^2 - 4e + 7)}{12} \right) + \frac{1}{2}m \left(\frac{u^2}{3}(1+e)^2 \right) \\ &= \frac{mu^2}{12}(e^2 - 4e + 7) + \frac{mu^2}{6}(e^2 + 2e + 1) \\ &= \frac{mu^2}{12} [e^2 - 4e + 7 + 2e^2 + 4e + 2] \\ &= \frac{mu^2}{12} [3e^2 + 9] \\ &= \frac{1}{4}mu^2(e^2 + 3) \end{aligned}$$

finally we have

$$\Rightarrow \frac{\frac{1}{4}mu^2(e^2 + 3)}{mu^2} = \frac{4}{5} \quad \leftarrow \text{"20\% lost"}$$

$$\Rightarrow \frac{1}{4}(e^2 + 3) = \frac{4}{5}$$

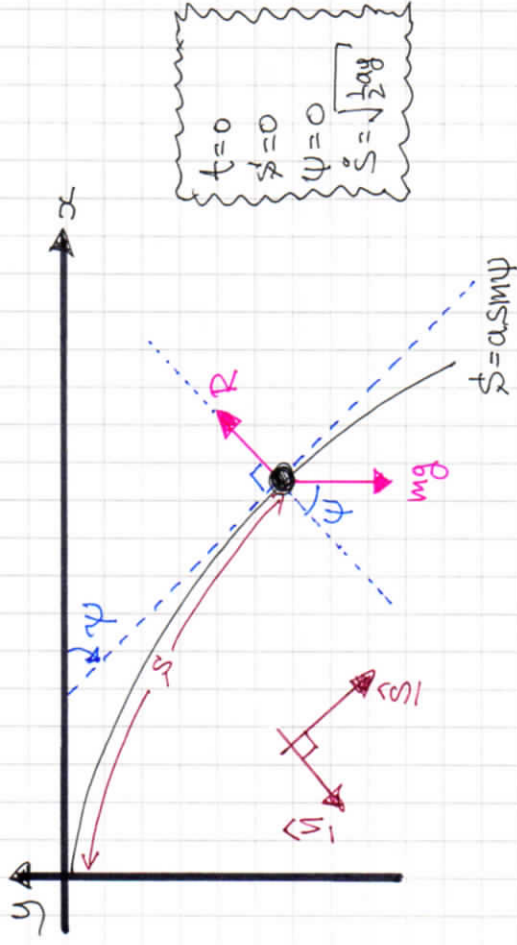
$$\Rightarrow e^2 + 3 = \frac{16}{5}$$

$$\Rightarrow \underline{\underline{e^2 = \frac{1}{5}}}$$

AS REQUIRED

LYGB - M456 PAPER C - QUESTION 7

a) START BY PUTTING ALL INFO INTO A DIAGRAM



CONSIDER/PREPARE THE USUAL AUXILIARIES

- $\dot{s} = a \sin \psi \Rightarrow r = \frac{ds}{d\psi} = a \cos \psi$
- $\underline{\underline{a}} = \ddot{s} \hat{s} + \frac{\dot{s}^2}{r} \hat{n}$

LOOKING AT THE TANGENTIAL MOTION ($\hat{s}$)

- $\Rightarrow m \ddot{s} = mg \sin \psi$
- $\Rightarrow \ddot{s} = g \sin \psi$

- $\Rightarrow \frac{1}{2} \frac{d(\dot{s}^2)}{ds} = g \left(\frac{s}{a} \right) \leftarrow \text{EQUATION OF MOTION}$
- $\Rightarrow \frac{d}{ds} (\dot{s}^2) = \frac{2g}{a} s$
- $\Rightarrow \left[\dot{s}^2 \right]_{\dot{s}=0}^{\dot{s}=v} = \int_0^s \frac{2g}{a} s \, ds$
- $\Rightarrow v^2 - \frac{1}{2} a g = \left[\frac{g}{a} s^2 \right]_0^s$
- $\Rightarrow v^2 - \frac{1}{2} a g = \frac{g}{a} s^2$
- $\Rightarrow v^2 = \frac{g}{a} s^2 + \frac{1}{2} a g$

LOOKING NEXT AT THE NORMAL DIRECTION ($\hat{n}$)

- $\Rightarrow m \frac{\dot{s}^2}{r} = mg \cos \psi - R$
- WITHIN IT GRANTS, $R=0$
- $\Rightarrow m \frac{\dot{s}^2}{r} = mg \cos \psi$
- $\Rightarrow \dot{s}^2 = g r \cos \psi$
- USING ABOVE EXPRESSION FOR $\dot{s}^2 = v^2$

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$$\Rightarrow \frac{g}{a} \dot{s}^2 + \frac{1}{2} a g = g (a \cos \psi) \cos \psi$$

$$\Rightarrow \frac{\dot{s}^2}{a} + \frac{1}{2} a = a \cos \psi$$

$$\Rightarrow 2\dot{s}^2 + a^2 = 2a^2 \cos^2 \psi$$

$$\Rightarrow 2\dot{s}^2 + a^2 = 2a^2 (1 - \sin^2 \psi)$$

$$\Rightarrow 2\dot{s}^2 + a^2 = 2a^2 \left(1 - \left(\frac{\dot{s}}{a}\right)^2\right)$$

$$\Rightarrow 2\dot{s}^2 + a^2 = 2a^2 \left(1 - \frac{\dot{s}^2}{a^2}\right)$$

$$\Rightarrow 2\dot{s}^2 + a^2 = 2a^2 - 2\dot{s}^2$$

$$\Rightarrow 4\dot{s}^2 = a^2$$

$$\Rightarrow \dot{s}^2 = \frac{1}{4} a^2$$

$$\Rightarrow \dot{s} = \frac{1}{2} a$$

b) FIRST WE HAVE

$$\text{AT } \dot{s} = \frac{1}{2} a \Rightarrow \frac{1}{2} a = a \sin \psi$$

$$\Rightarrow \sin \psi = \frac{1}{2}$$

$$\Rightarrow \psi = \frac{\pi}{6}$$

NORMAL ACCELERATION (\ddot{s}) IS SIMPLY \ddot{s}

$$\Rightarrow \ddot{s} = g \sin \psi \quad (\text{FROM EQUATION})$$

$$\Rightarrow \ddot{s} = g \times \sin \frac{\pi}{6}$$

$$\Rightarrow \ddot{s} = \frac{1}{2} g$$

TANGENTIAL ACCELERATION IS \frac{\dot{s}^2}{r}

$$\Rightarrow \frac{\dot{s}^2}{r} = \frac{\frac{g}{a} \dot{s}^2 + \frac{1}{2} a g}{a \cos \psi}$$

$$\Rightarrow \frac{\dot{s}^2}{r} = \frac{\frac{g}{a} \left(\frac{1}{2} a\right)^2 + \frac{1}{2} a g}{a \cos \frac{\pi}{6}} = \frac{\frac{3}{4} a g}{a \frac{\sqrt{3}}{2}} = \frac{\sqrt{3}}{2} g$$

THENCE THE MAGNITUDE OF THE ACCELERATION

CAN BE FOUND AS

$$\sqrt{\left(\frac{1}{2} g\right)^2 + \left(\frac{\sqrt{3}}{2} g\right)^2} = \sqrt{\frac{1}{4} g^2 + \frac{3}{4} g^2} = g$$

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1YGB - M456 PAPER C - QUESTION 8

$$\underline{F}_1 = (3a+1)\underline{i} + 3\underline{j} \quad \text{AT} \quad A(1,2)$$

$$\underline{F}_2 = (a-10)\underline{i} - 2\underline{j} \quad \text{AT} \quad B(2,0)$$

$$\underline{F}_3 = \underline{i} + (1-a)\underline{j} \quad \text{AT} \quad C(4,-1)$$

a) IF THE SYSTEM IS TO REDUCE TO A COUPLE ABOUT O

$$\underline{F}_1 + \underline{F}_2 + \underline{F}_3 = (0,0)$$

$$(3a+1, 3) + (a-10, -2) + (1, 1-a) = (0,0)$$

$$(4a-8, 2-a) = (0,0)$$

THIS IS INDEED POSSIBLE IF $a=2$

FINDING THE MOMENT ABOUT O, WITH $a=2$

$$\begin{vmatrix} \underline{i} & \underline{j} & \underline{k} \\ 1 & 2 & 0 \\ 7 & 3 & 0 \end{vmatrix} + \begin{vmatrix} \underline{i} & \underline{j} & \underline{k} \\ 2 & 0 & 0 \\ -8 & -2 & 0 \end{vmatrix} + \begin{vmatrix} \underline{i} & \underline{j} & \underline{k} \\ 4 & -1 & 0 \\ 1 & -1 & 0 \end{vmatrix}$$

$$= [0, 0, 3-14] + [0, 0, -4] + [0, 0, -4+1]$$

$$= [0, 0, -11] + [0, 0, -4] + [0, 0, -3]$$

$$= [0, 0, -18]$$

HENCE, A MAGNITUDE OF 18 Nm, ANTICLOCKWISE

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b) NOW FIND THE MOMENT OF THE FORCES ABOUT O, IN TERMS OF a

$$\underline{G}_O = \begin{vmatrix} \underline{i} & \underline{j} & \underline{k} \\ 1 & 2 & 0 \\ 3a+1 & 3 & 0 \end{vmatrix} + \begin{vmatrix} \underline{i} & \underline{j} & \underline{k} \\ 2 & 0 & 0 \\ a-10 & -2 & 0 \end{vmatrix} + \begin{vmatrix} \underline{i} & \underline{j} & \underline{k} \\ 4 & -1 & 0 \\ 1 & 1-a & 0 \end{vmatrix}$$

$$\underline{G}_O = (0, 0, 3-6a-2) + (0, 0, -4) + (0, 0, 4-4a+1)$$

$$\underline{G}_O = (0, 0, 1-6a) + (0, 0, -4) + (0, 0, 5-4a)$$

$$\underline{G}_O = (0, 0, 2-10a)$$

THIS YIELDS ZERO MOMENT IF $a = \frac{1}{5}$

$$\begin{aligned} \text{THM } \underline{F}_1 + \underline{F}_2 + \underline{F}_3 &= (4a-8, 2-a) \leftarrow \text{from earlier} \\ &= \left(-\frac{36}{5}, \frac{9}{5}\right) \end{aligned}$$

THIS LINE PASSES THROUGH THE ORIGIN (ZERO MOMENT ABOUT O)

$$y = mx + \cancel{c}$$

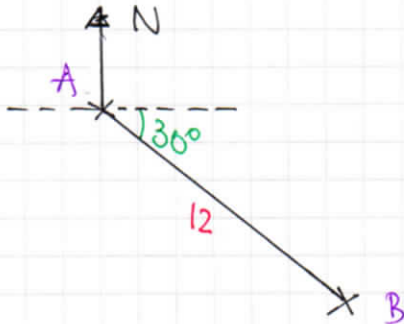
$$m = \frac{\frac{9}{5} - 0}{-\frac{36}{5} - 0} = -\frac{1}{4}$$

$\therefore$ REDUCES TO $\underline{F} = -\frac{36}{5}\underline{i} + \frac{9}{5}\underline{j}$, WHICH ACTS

ALONG THE LINE $y = -\frac{1}{4}x$

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INITIAL CONFIGURATION



VELOCITY TRIANGLE

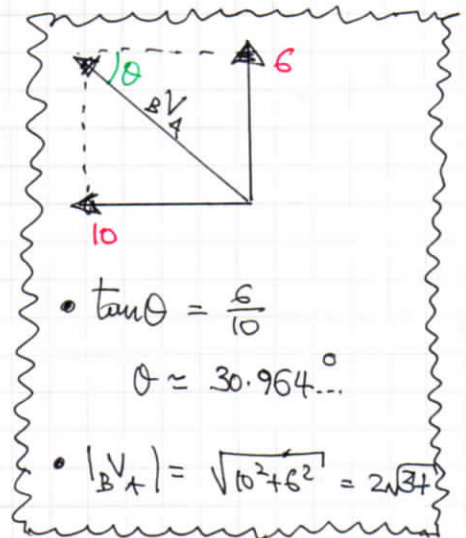
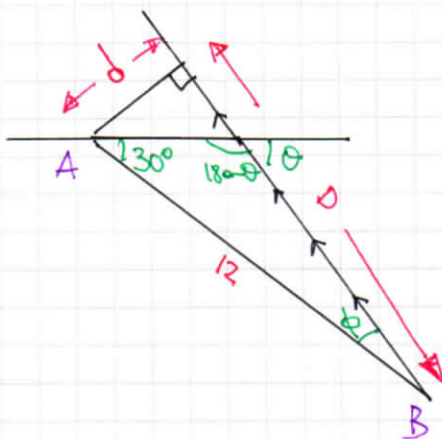
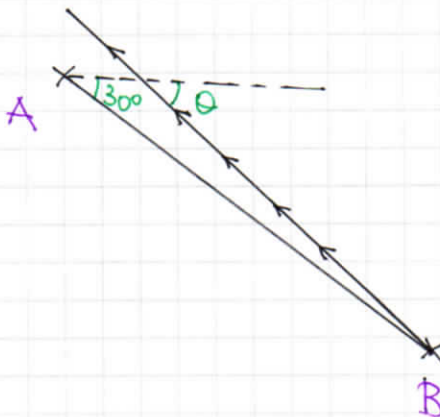
$$\underline{V}_{B/A} = \underline{V}_B - \underline{V}_A$$

$$(\underline{V}_B = \underline{V}_A + \underline{V}_{B/A})$$

$$\underline{V}_{B/A} = (-3\hat{i} + 9\hat{j}) - (7\hat{i} + 3\hat{j})$$

$$\underline{V}_{B/A} = -10\hat{i} + 6\hat{j}$$

FIXING A, AN OBSERVER ON A SEES THE FOLLOWING



SHORTEST DISTANCE d IS

$$d = 12 \sin \phi$$

$$d = 12 \sin(0.96375^\circ)$$

$$d \approx 0.2018 \dots \text{ km}$$

$$d \approx 202 \text{ m}$$

$$\phi + 30 + 180 - \theta = 180$$

$$\phi = \theta - 30$$

$$\phi = 0.96375^\circ$$

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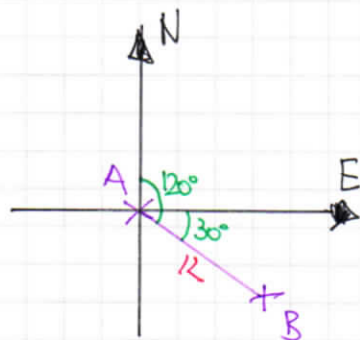
- $D = 12 \cos \phi = 12 \cos(0.96375 \dots) = 11.9983024 \dots \text{ km}$
- COVERED AT $2\sqrt{34} \text{ km h}^{-1}$ WE OBTAIN

$$\begin{aligned} \frac{11.9983024 \dots}{2\sqrt{34}} &\approx 1.0288 \dots \text{ HOUR} \\ &\approx 1 \text{ HOUR} - 2 \text{ MINUTES} \\ &\approx \underline{\underline{13:02}} \end{aligned}$$

ALTERNATIVE BY VECTORS

- TAKE THE POSITION OF "A" AT NOON, TO BE THE ORIGIN $\rightarrow$ THE POSITION VECTOR OF "B" AT NOON WILL BE

$$\underline{r}_B = (\underbrace{12 \cos 30}_{6\sqrt{3}})\underline{i} - (\underbrace{12 \sin 30}_{6})\underline{j}$$



- THE POSITION VECTORS OF THE TWO SHIPS, t HOURS AFTER NOON, IS

$$\underline{r}_A = (0, 0) + (7, 3)t = (7t, 3t)$$

$$\underline{r}_B = (6\sqrt{3}, -6) + (-3, 4)t = (6\sqrt{3} - 3t, 4t - 6)$$

- THE POSITION VECTOR OF B, RELATIVE TO A IS GIVEN BY

$$\underline{r}_B - \underline{r}_A = (6\sqrt{3} - 10t, 4t - 6)$$

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- THE DISTANCE BETWEEN THE SHIPS AT TIME t

$$d = |\vec{r}_B - \vec{r}_A|$$

$$d = |6\sqrt{3} - 10t, 6t - 6|$$

$$d = \sqrt{(6\sqrt{3} - 10t)^2 + (6t - 6)^2}$$

$$d = \sqrt{108 - 120\sqrt{3}t + 100t^2 + 36t^2 - 72t + 36}$$

$$d = \sqrt{136t^2 - (72 + 120\sqrt{3})t + 144}$$

$$d^2 = 136t^2 - 24(3 + 5\sqrt{3})t + 144$$

- LET $f(t) = 136t^2 - 24(3 + 5\sqrt{3})t + 144$
BY COMPLETING THE SQUARE OF CANNON

$$f'(t) = 272t - 24(3 + 5\sqrt{3})$$

- SOLVING FOR ZERO YEARS

$$\begin{aligned} t &= \frac{24(3 + 5\sqrt{3})}{272} \approx 1.0288... \\ &\approx 1 \text{ HOUR} - 2 \text{ MINUTES} \\ &\approx \underline{\underline{13:02}} \end{aligned}$$

- AND TO FIND THE MINIMUM DISTANCE

$$\begin{aligned} d_{\min} &= \sqrt{136(1.0288...)^2 - (72 + 120\sqrt{3})(1.0288...) + 144} \\ &\approx 0.201839... \text{ km} \\ &\approx \underline{\underline{202 \text{ m}}} \end{aligned}$$

1YGB - M456 PAPER 2 - QUESTION 10

a)

$$F = \frac{25}{x^2} - \frac{50}{x^3}, \quad x > 0$$

WORK BY $F = -4$

$$\Rightarrow \int_1^k \left(\frac{25}{x^2} - \frac{50}{x^3} \right) dx = -4$$

$$\Rightarrow \left[-\frac{25}{x} + \frac{25}{x^2} \right]_1^k = -4$$

$$\Rightarrow \left(-\frac{25}{k} + \frac{25}{k^2} \right) - \left(-25 + 25 \right) = -4 \quad \swarrow \times k^2$$

$$\Rightarrow -25k + 25 = -4k^2$$

$$\Rightarrow 4k^2 - 25k + 25 = 0$$

$$\Rightarrow (4k - 5)(k - 5) = 0$$

$$\Rightarrow k = \begin{cases} 5 \\ \frac{5}{4} \end{cases}$$

b)

$F = 0$ YIELDS

$$\frac{25}{x^2} - \frac{50}{x^3} = 0$$

$$25x - 50 = 0$$

$$\underline{x = 2}$$

NEXT THE WORK FROM $x=1$ TO $x=2$

$$W = \int_1^2 \left(\frac{25}{x^2} - \frac{50}{x^3} \right) dx = \left[-\frac{25}{x} + \frac{25}{x^2} \right]_1^2$$

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$$= \left(-\frac{25}{2} + \frac{25}{4} \right) - \cancel{(-25 + 25)} = -\frac{25}{4} \quad (\text{1+ work out})$$

By Energy

$$\Rightarrow KE_{x=1} - W_{\text{out}} = KE_{x=2}$$

$$\Rightarrow \frac{1}{2}mu^2 - \frac{25}{4} = \frac{1}{2}mv^2$$

$$\Rightarrow \frac{1}{2}(0.5) \times 13^2 - \frac{25}{4} = \frac{1}{2}(0.5)v^2$$

$$\Rightarrow \frac{169}{4} - \frac{25}{4} = \frac{1}{4}v^2$$

$$\Rightarrow 169 - 25 = v^2$$

$$\Rightarrow v^2 = 144$$

$$\Rightarrow \underline{|v| = 12 \text{ ms}^{-1}}$$

1YGB - M456 PAPER C - QUESTION 11

$$r = k e^{\theta \cot \alpha}$$

$$(k, \alpha \text{ constants}, 0 < \alpha \leq \frac{\pi}{4})$$

CONSTANT ANGULAR VELOCITY

$$\dot{\theta} = \omega$$

$$\ddot{\theta} = 0$$

DIFFERENTIATE THE EQUATION OF THE PATH TO OBTAIN $\dot{r}$ & $\ddot{r}$

$$\Rightarrow r = k e^{\theta \cot \alpha}$$

$$\Rightarrow \dot{r} = k e^{\theta \cot \alpha} \times \dot{\theta} \cot \alpha$$

$$\Rightarrow \dot{r} = r \omega \cot \alpha$$

$$\Rightarrow \ddot{r} = \dot{r} \omega \cot \alpha = (r \omega \cot \alpha) \omega \cot \alpha$$

$$\Rightarrow \ddot{r} = r \omega^2 \cot^2 \alpha$$

NOW THE ACCELERATION IN POLARS IS GIVEN BY

$$\Rightarrow \underline{\ddot{r}} = (\ddot{r} - r \dot{\theta}^2) \underline{\hat{r}} + \frac{1}{r} \frac{d}{dt}(r^2 \dot{\theta}) \underline{\hat{\theta}}$$

$$\Rightarrow \underline{\ddot{r}} = (\ddot{r} - r \omega^2) \underline{\hat{r}} + \frac{1}{r} \frac{d}{dt}(r^2 \omega) \underline{\hat{\theta}}$$

$$\Rightarrow \underline{\ddot{r}} = (\ddot{r} - r \omega^2) \underline{\hat{r}} + 2 \dot{r} \omega \underline{\hat{\theta}}$$

$$\Rightarrow \underline{\ddot{r}} = (r \omega^2 \cot^2 \alpha - \omega^2 r) \underline{\hat{r}} + (2 \omega^2 r \cot \alpha) \underline{\hat{\theta}}$$

$$\Rightarrow \underline{\ddot{r}} = r \omega^2 \left[(\cot^2 \alpha - 1) \underline{\hat{r}} + [2 \cot \alpha] \underline{\hat{\theta}} \right]$$

NEXT THE MODULUS (MAGNITUDE OF ACCELERATION)

$$\Rightarrow |\underline{\ddot{r}}| = \left| r \omega^2 \left[(\cot^2 \alpha - 1) \underline{\hat{r}} + (2 \cot \alpha) \underline{\hat{\theta}} \right] \right|$$

$$\Rightarrow |\underline{\ddot{r}}| = r \omega^2 \left[(\cot^2 \alpha - 1)^2 + (2 \cot \alpha)^2 \right]^{\frac{1}{2}}$$

IYGB - M456 PAPER C - QUESTION 11

$$\Rightarrow |\ddot{\underline{r}}| = r\omega^2 \left[\omega^4 t_\alpha^4 - 2\omega^2 t_\alpha^2 + 1 + 4\omega^2 t_\alpha^2 \right]^{\frac{1}{2}}$$

$$\Rightarrow |\ddot{\underline{r}}| = r\omega^2 \left[\omega^4 t_\alpha^4 + 2\omega^2 t_\alpha^2 + 1 \right]^{\frac{1}{2}}$$

$$\Rightarrow |\ddot{\underline{r}}| = r\omega^2 \sqrt{(\omega^2 t_\alpha^2 + 1)^2}$$

$$\Rightarrow |\ddot{\underline{r}}| = r\omega^2 \csc^2 \alpha$$

NEXT WE REQUIRE A VELOCITY EXPRESSION, TO GET THE SPEED

$$\Rightarrow \underline{v} = \dot{r}\hat{r} + r\dot{\theta}\hat{\theta}$$

$$\Rightarrow \underline{v} = (r\omega t_\alpha)\hat{r} + r\omega\hat{\theta}$$

$$\Rightarrow |\underline{v}| = |r\omega(\omega t_\alpha \hat{r} + \hat{\theta})|$$

$$\Rightarrow |\underline{v}| = r\omega \sqrt{\omega^2 t_\alpha^2 + 1}$$

$$\Rightarrow |\underline{v}| = r\omega \sqrt{\csc^2 \alpha}$$

$$\Rightarrow |\underline{v}| = r\omega \csc \alpha$$

FINALLY WE OBTAIN

$$|\ddot{\underline{r}}| = r\omega^2 \csc^2 \alpha = \frac{1}{r} (r^2 \omega^2 \csc^2 \alpha) = \frac{|\underline{v}|^2}{r}$$

$$\therefore |\ddot{\underline{r}}| = \frac{|\underline{v}|^2}{r}$$

AS REQUIRED

-1-

YGB - M456 PAPER C - QUESTION 12

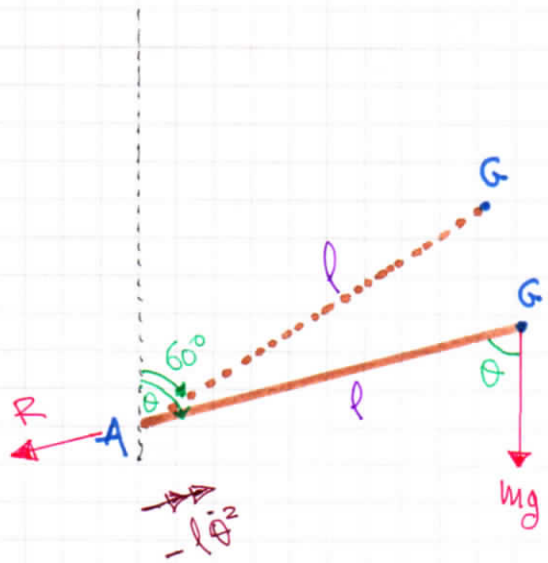
- a) STARTING WITH A DIAGRAM,
WHERE G DENOTES THE MIDPOINT
OF THE ROD

$$I_A = \frac{4}{3}ml^2$$

$$12ma^2 = \frac{4}{3}ml^2$$

$$l^2 = 9a^2$$

$$l = 3a$$



BY CONSERVING TAKING THE LEVEL OF "A" AS THE ZERO POTENTIAL LEVEL

$$\Rightarrow P.E_{60^\circ} + \cancel{P.E_{60^\circ}} = K.E_\theta + P.E_\theta$$

$$\Rightarrow mgl \cos 60^\circ = \frac{1}{2}I\dot{\theta}^2 + mgl \cos \theta$$

$$\Rightarrow mg(3a) \times \frac{1}{2} = \frac{1}{2}(12ma^2)\dot{\theta}^2 + mg(3a)\cos \theta$$

$$\Rightarrow \frac{3}{2}mga = 4ma^2\dot{\theta}^2 + 3mga \cos \theta$$

$$\Rightarrow 3g = 8a\dot{\theta}^2 + 6g \cos \theta$$

$$\Rightarrow 8a\dot{\theta}^2 = 3g - 6g \cos \theta$$

$$\Rightarrow 8a\dot{\theta}^2 = 3g(1 - 2\cos \theta)$$

$$\Rightarrow \dot{\theta}^2 = \frac{3g}{8a}(1 - 2\cos \theta)$$

IYGB - M456 PAPER C - QUESTION 12

b) LOOKING IN THE RADIAL DIRECTION

$$\Rightarrow "m\ddot{r} = \text{RESULTANT FORCE}"$$

$$\Rightarrow m(-3a\dot{\theta}^2) = -R - mg\cos\theta$$

$$\Rightarrow R = 3ma\dot{\theta}^2 - mg\cos\theta$$

$$\Rightarrow R = 3ma\left(\frac{3g}{8a}(1-2\cos\theta)\right) - mg\cos\theta$$

$$\Rightarrow R = \frac{9}{8}mg(1-2\cos\theta) - mg\cos\theta$$

$$\Rightarrow R = \frac{1}{8}mg(9-18\cos\theta-8\cos\theta)$$

$$\Rightarrow R = \frac{1}{8}mg(9-26\cos\theta)$$

HENCE THE REQUIRED COMPONENT IS

$$\frac{1}{8}mg(9-26\cos\theta), \text{ RADIALY INWARDS}$$

OR

$$\frac{1}{8}mg(26\cos\theta-9), \text{ RADIALY OUTWARDS}$$

-1-

1YGB - M456 PAPER C - QUESTION 13

a) SOLVING THE DIFFERENTIAL EQUATION

$$\Rightarrow m\ddot{x} = mg - kmv$$

$$\Rightarrow \ddot{x} = g - kv$$

$$\Rightarrow v \frac{dv}{dx} = g - kv$$

$$\Rightarrow \frac{v}{g - kv} dv = 1 dx$$

$$\Rightarrow \frac{-kv}{g - kv} dv = -k dx$$

$$\Rightarrow \int_{v=0}^v \frac{-kv}{g - kv} dv = \int_{x=0}^x -k dx$$

$$\Rightarrow \int_0^v \frac{(g - kv) - g}{g - kv} dv = \int_0^x -k dx$$

$$\Rightarrow \int_0^v 1 - \frac{g}{g - kv} dv = \int_0^x -k dx$$

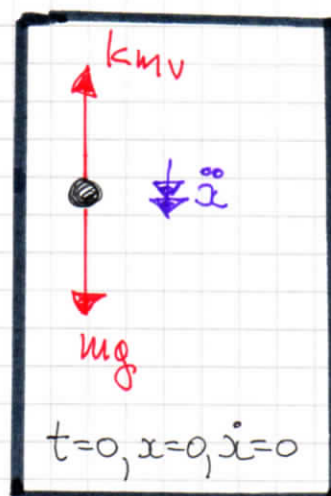
$$\Rightarrow \left[v + \frac{g}{k} \ln|g - kv| \right]_0^v = \left[-kx \right]_0^x$$

$$\Rightarrow \left[v + \frac{g}{k} \ln|g - kv| \right] - \left[\frac{g}{k} \ln g \right] = -kx - 0$$

$$\Rightarrow v + \frac{g}{k} \ln \left| \frac{g - kv}{g} \right| = -kx$$

$$\Rightarrow x = -\frac{1}{k} v - \frac{g}{k^2} \ln \left| \frac{g - kv}{g} \right|$$

$$\Rightarrow x = \frac{g}{k^2} \ln \left| \frac{g}{g - kv} \right| - \frac{v}{k}$$



to require

1YGB - M456 PART C - QUESTION 13

b) LOOKING AT THE ORIGINAL O.D.E

$$\ddot{x} = g - kv$$

LIMITING SPEED $\Rightarrow \ddot{x} = 0$
 $\Rightarrow V = \frac{g}{k}$

THUS WE HAVE IF $v = \frac{1}{2}V = \frac{g}{2k}$

$$x = \frac{g}{k^2} \ln \left| \frac{g}{g - kv} \right| - \frac{v}{k}$$

$$x = \frac{g}{k^2} \ln \left| \frac{g}{g - k \frac{g}{2k}} \right| - \frac{\frac{g}{2k}}{k}$$

$$x = \frac{g}{k^2} \ln 2 - \frac{g}{2k^2}$$

$$x = \frac{g}{2k^2} [2 \ln 2 - 1]$$

$$x = \frac{1}{2g} \times \frac{g^2}{k^2} [\ln 4 - 1]$$

$$x = \frac{1}{2g} V^2 [\ln 4 - 1]$$

$x = \frac{V^2}{2g} [-1 + \ln 4]$

AS REQUIRED

1YGB - M456 PAPER C - QUESTION 14

LOOKING AT THE DIAGRAM BELOW



MOMENT OF INERTIA OF THE SPHERE

$$I_o = \frac{2}{5}ma^2$$

$$I_p = \frac{2}{5}ma^2 + ma^2 = \frac{7}{5}ma^2$$

LET THE ANGULAR VELOCITY ABOUT P, BE Ω

BY CONSERVATION OF MOMENTUM ABOUT P

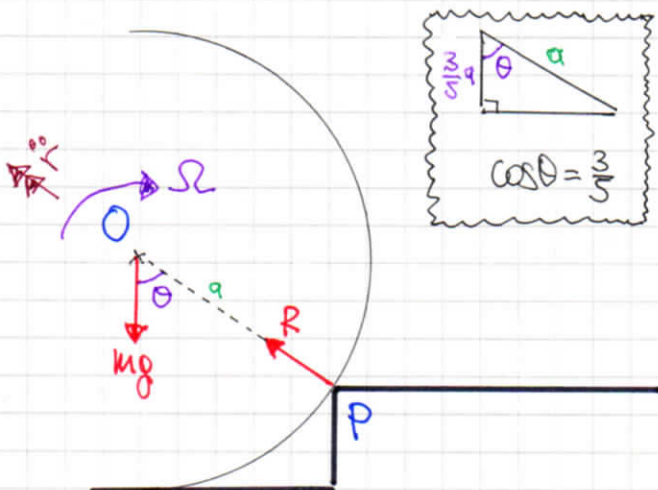
$$\Rightarrow \underbrace{(I_o \omega) + (mV) \times \frac{3}{5}a}_{\text{JUST BEFORE IMPACT}} = \underbrace{I_p \Omega}_{\text{AFTER IMPACT AT P}}$$

$$\Rightarrow \frac{2}{5}ma^2\omega + \frac{3}{5}mVa = \frac{7}{5}ma^2\Omega$$

$$\Rightarrow \boxed{2a\omega + 3V = 7a\Omega}$$

$\div \frac{1}{5}ma$

NEXT WE CONSIDER THE INSTANT AFTER THE IMPACT



RADIALLY, AS IT ROTATES ABOUT P

$$\Rightarrow m\ddot{r} = R - mg\cos\theta$$

$$\Rightarrow m(-\Omega^2 a) = R - mg\cos\theta$$

$$\Rightarrow R = mg\cos\theta - ma\Omega^2$$

1YGB - M456 PAPER C - QUESTION 14

FOR ROTATION ABOUT P, $R > 0$

$$\Rightarrow \frac{3}{5}mg - ma\Omega^2 > 0$$

$$\Rightarrow a\Omega^2 < \frac{3}{5}g$$

$$\Rightarrow 49a^2\Omega^2 < \frac{147}{5}ag$$

$$\Rightarrow (2aw + 3v)^2 < \frac{147}{5}ag$$

$$\Rightarrow \left(2a\frac{V}{a} + 3v\right)^2 < \frac{147}{5}ag$$

$$\Rightarrow (5v)^2 < \frac{147}{5}ag$$

$$\Rightarrow 25v^2 < \frac{147}{5}ag$$

$$\Rightarrow \underline{v^2 < \frac{147}{125}ag}$$

As required

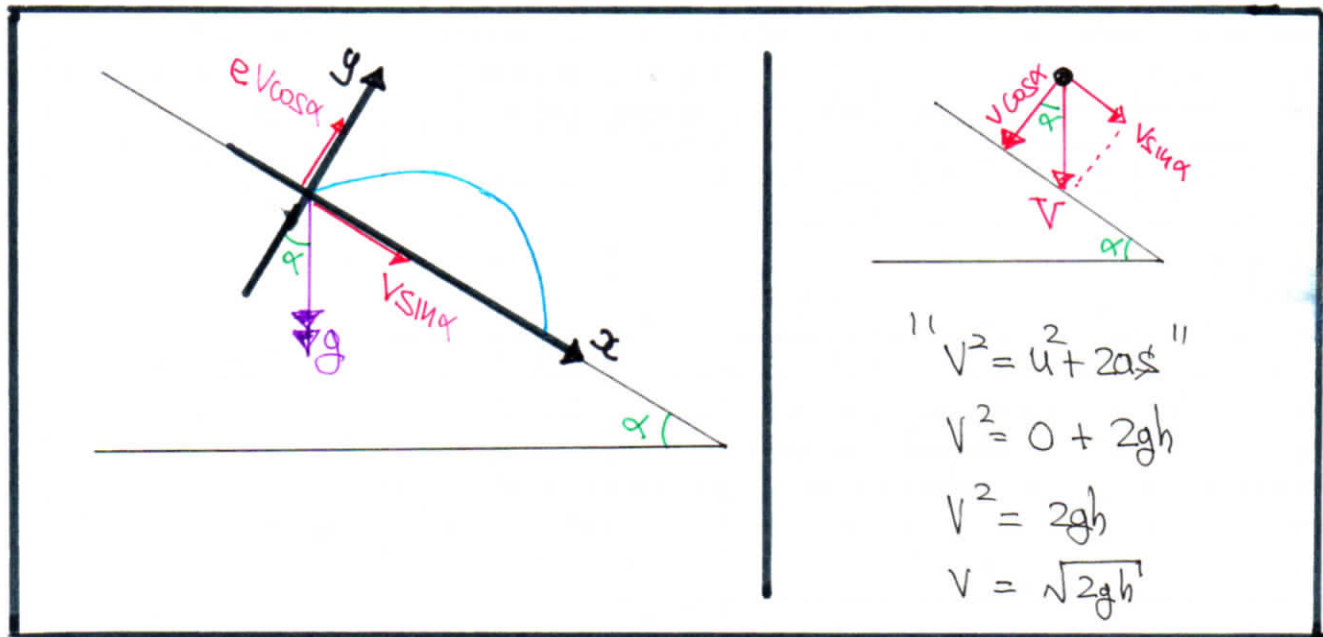
IN ORDER TO "CRATE"

$$\underline{7aw = 2aw + 3v}$$

OBTAINED RESULT

- 1 -

1YGB - M456 PAPER C - QUESTION 15



- START BY COMPUTING THE COMPONENTS OF THE VELOCITY ON IMPACT, PARALLEL & PERPENDICULAR TO THE PLANE (TOP RIGHT). — NO MOMENTUM IS EXCHANGED PARALLEL TO THE PLANE HOWEVER PERPENDICULAR TO THE PLANE THE "REBOUNDING" VELOCITY COMPONENT IS $eV \cos \alpha$ (TOP LEFT)

- DERIVE THE EQUATIONS OF MOTION IN THE CO-ORDINATE SYSTEM SHOWN IN THE ABOVE DIAGRAM

• $\ddot{x} = g \sin \alpha$ • $\dot{x} = gt \sin \alpha + V \sin \alpha$ • $x = \frac{1}{2}gt^2 \sin \alpha + Vt \sin \alpha$	• $\ddot{y} = -g \cos \alpha$ • $\dot{y} = -gt \cos \alpha + eV \cos \alpha$ • $y = -\frac{1}{2}gt^2 \cos \alpha + eVt \cos \alpha$
---	--

- DETERMINE THE FLIGHT TIME TO THE "SECOND" IMPACT, I.E. $y=0$

$$\Rightarrow 0 = -\frac{1}{2}gt^2 \cos \alpha + eVt \cos \alpha$$

$$\Rightarrow 0 = \frac{1}{2}t \cos \alpha [2eV - gt]$$

$$\Rightarrow \underline{t = \frac{2eV}{g}} \quad (t \neq 0)$$

1 VGB - M456 PAPER C - QUESTION 15

● SUBSTITUTING INTO THE "x-EQUATION" TO FIND THE REQUIRED DISTANCE d

$$d = \frac{1}{2}g\left(\frac{2ev}{g}\right)^2 \sin\alpha + v\left(\frac{2ev}{g}\right)\sin\alpha$$

$$d = \frac{2e^2v^2}{g}\sin\alpha + \frac{2ev^2}{g}\sin\alpha$$

$$d = \left(\frac{2ev^2}{g}\sin\alpha\right)(e+1)$$

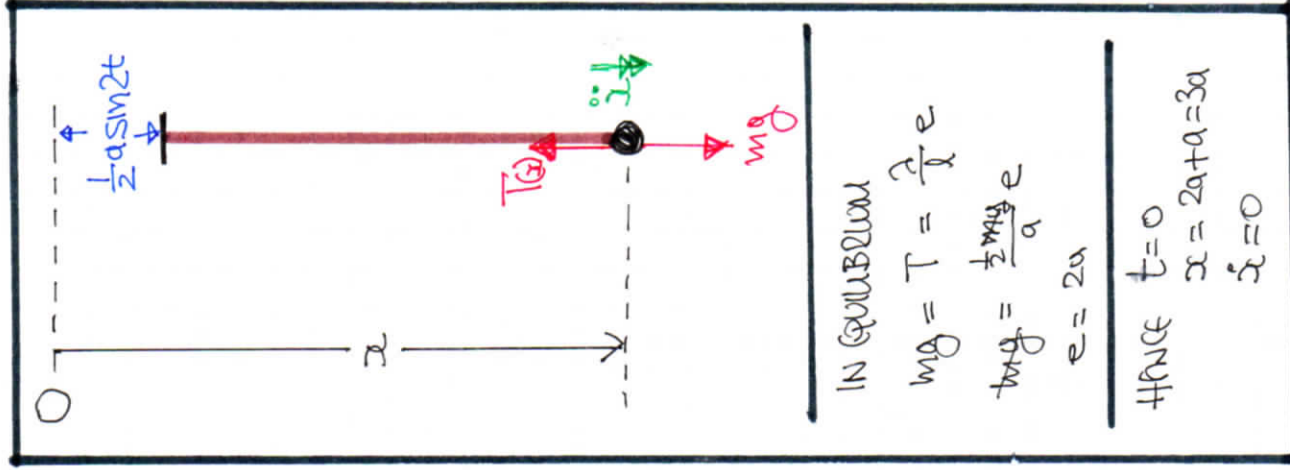
$$d = \frac{2e}{g}(2gh)(\sin\alpha)(e+1)$$

$$d = 4eh(e+1)\sin\alpha$$

$$v = \sqrt{2gh}$$

$$v^2 = 2gh$$

YGB - M456 PART C - QUESTION 16



LOOKING AT THE DIAGRAM,
FORM THE EQUATION OF MOTION

$$\Rightarrow m\ddot{x} = mg - T$$

$$\Rightarrow m\ddot{x} = mg - \frac{\lambda}{a}(x - a - \frac{1}{2}a\sin 2t)$$

$$\Rightarrow m\ddot{x} = mg - \frac{\frac{1}{2}mg}{a}(x - a - \frac{1}{2}a\sin 2t)$$

$$\Rightarrow \ddot{x} = g - \frac{g}{2a}(x - a - \frac{1}{2}a\sin 2t)$$

$$\Rightarrow \ddot{x} = g - \frac{gx}{2a} + \frac{1}{2}g + \frac{1}{4}g\sin 2t$$

$$\Rightarrow \ddot{x} + \frac{g}{2a}x = \frac{3}{2}g + \frac{1}{4}g\sin 2t$$

LET $\omega^2 = \frac{g}{2a} \Rightarrow g = 2a\omega^2$

$$\Rightarrow \ddot{x} + \omega^2 x = \frac{3}{2}(2a\omega^2) + \frac{1}{4}(2a\omega^2)\sin 2t$$

$$\Rightarrow \ddot{x} + \omega^2 x = 3a\omega^2 + \frac{1}{2}a\omega^2\sin 2t$$

THE COMPLEMENTARY FUNCTION IS THE
STANDARD S.H.M SOLUTION

$$x = A\cos \omega t + B\sin \omega t$$

FOR PARTICULAR INTEGRAL WE TRY

- $x = P + Q\sin 2t$
- $\ddot{x} = -4Q\sin 2t$

$$\Rightarrow -4Q\sin 2t + \omega^2(P + Q\sin 2t) \equiv 3a\omega^2 + \frac{1}{2}a\omega^2\sin 2t$$

$$\Rightarrow P\omega^2 + (Q\omega^2 - 4Q)\sin 2t \equiv 3a\omega^2 + \frac{1}{2}a\omega^2\sin 2t$$

$$\Rightarrow P = 3a \quad \& \quad Q(\omega^2 - 4) = \frac{1}{2}a\omega^2$$

$$Q = \frac{a\omega^2}{2(\omega^2 - 4)}$$

NGB - MUSE PAPER C - QUESTION 16

HENCE THE GENERAL SOLUTION IS GIVEN BY

$$x = A \cos \omega t + B \sin \omega t + 3a + \frac{a\omega^2}{2(\omega^2 - 4)} \sin 2t$$

APPLY $t=0, \dot{x}=3a$

$$3a = A + 3a$$

$$A=0$$

$$x = 3a + B \sin \omega t + \frac{a\omega^2}{2(\omega^2 - 4)} \sin 2t$$

DIFFERENTIATE AND APPLY CONDITION $t=0, \dot{x}=0$

$$\dot{x} = B\omega \cos \omega t + \frac{a\omega^2}{\omega^2 - 4} \cos 2t$$

$$0 = B\omega + \frac{a\omega^2}{\omega^2 - 4}$$

$$B = -\frac{a\omega}{\omega^2 - 4}$$

$$x = 3a + \frac{a\omega^2}{2(\omega^2 - 4)} \sin 2t - \frac{a\omega}{\omega^2 - 4} \sin \omega t$$

$$x = 3a + \frac{a\omega}{2(\omega^2 - 4)} [\omega \sin 2t - 2 \sin \omega t]$$